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MATTEO LUPERTO CURRICULUM VITAE

INFORMAZIONI PERSONALI (NON INSERIRE INDIRIZZO PRIVATO E TELEFONO FISSO O CELLULARE)

COGNOME	LUPERTO
NOME	MATTEO
DATA DI NASCITA	[22, 01, 1988]

Data

20/02/2019

Luogo

Milano

Matteo Luperto

<i>Name</i>	Matteo Luperto
<i>Date of birth</i>	22/01/1988
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Highlights

- Post-doc at Applied Intelligent System Laboratory (AISLab), Dipartimento di Informatica Giovanni Degli Antoni, Università degli Studi di Milano, since March 2017.
- Ph.D. in Information Technology from Artificial Intelligence and Robotics Lab (AIRLab), Dipartimento di Elettronica, Informazione e Bioingegneria, Politecnico di Milano (2017). Advisor prof. Francesco Amigoni.
- Research interests in *semantic mapping* for autonomous mobile robots, focusing on techniques to retrieve the 2D structure of indoor buildings by exploiting a priori knowledge using machine learning and AI techniques.
- Researcher for the H2020 research project *MoveCare*, Multiple-Actors Virtual Empathic Caregiver for the Elder, since November 2016. The project, which involves a consortium of 12 European partners, aims to develop a framework integrating a robotic platform with an IoT-based domotic system and a virtual caregiver, in order to provide transparent monitoring and social interventions for elders at home. A 3 months pilot with 30 end-users and 15 autonomous mobile robots will be held in Spain and in Italy during the last year of the project, 2019.
- Winner of the 2012 RoboCup Virtual Robot Competition Rescue Simulation League in Mexico City, Mexico. I was part of the Politecnico di Milano team under the supervision of prof. F. Amigoni. I was in charge of the task of semantic reasoning and improving multi-robot autonomous exploration by using semantic knowledge.
- Publications: 2 papers in peer-reviewed international journals, 9 conference papers, 7 workshop and demo papers, and 2 technical papers. Academic age: 5 years.
- Organization and management of four pilot trial experiments with end-users in a study for cognitive assessment and stimulation of elderly people using a framework that integrates digital activities and an autonomous mobile robot. These pilot studies, with more than 100 subjects evaluated since September 2017, are performed with joint collaboration with Policlinico IRCCS Ca' Granda Milano, University of Manchester, University of Plymouth, Politecnico di Milano, and Università degli Studi di Milano, within the MoveCare project.
- Cosupervisor of 11 master theses at Politecnico di Milano.
- Teaching assistant for undergraduate course of Informatica B (2013-2017) and Fondamenti di Informatica (since 2014) at Politecnico di Milano.

Short bio

Matteo Luperto (Garbagnate Milanese, Italy, 22 January 1988) is a postdoctoral researcher with the Dipartimento di Informatica Giovanni Degli Antoni at the Università Statale di Milano (Italy). He received his Ph.D. in Information Technology from the Politecnico di Milano (Italy) in 2017. His main research interest is in *semantic mapping for autonomous mobile robots* and *assistive and collaborative mobile robotics*.

Position and Education

RECORD OF EMPLOYMENT

November 2016 – present

Research assistant (post-doc) at the Dipartimento di Informatica Giovanni Degli Antoni, Università degli Studi di Milano, Applied Intelligent System Lab (AISLab - prof. A. Borghese), working on the H2020 Project “MoveCare - Multiple-Actors Virtual Empathic Caregiver for the Elder”, Programme H2020-ICT-26b-2016.

MoveCare integrates an autonomous robotic platform, developed for the project, with an IoT-based domotic system, smart objects, a virtual community, and an activity center to provide, through artificial intelligence, assistance, activities, and transparent monitoring to the elder at home. A pilot study, with the deployment of the full architecture of the system and using 15 autonomous mobile robots for 3 consecutive months, will be held, inside the house of 30 end-users both in Spain and in Italy, during the last year of the project, 2019.

Role: Development of the community-based activity center, development and testing of digitalized cognitive tests for transparent cognitive evaluation of elders at home, integration of the community based activity center with the robotic platform and domotic sensors, integration of the IoT platform and of the cloud-based cognitive activities with the autonomous robot, development of functionalities for the robot, testing and evaluation of the MoveCare framework in pre-pilot studies with end-users for continuous integration, and integration between all components developed by the partner of the MoveCare consortium for the final pilot.

November 2013 – November 2016

Ph.D. student at the Artificial Intelligence and Robotics Lab (AIRLab), Dipartimento di Elettronica Informazione e Bioingegneria, Politecnico di Milano. Advisor: prof. Francesco Amigoni. Research topic: Semantic modeling of indoor environments for autonomous mobile robots integrating a priori knowledge about the structure of the building.

February 2013 – September 2013

Internship at the HOC-LAB - Hypermedia Open CenterLab - Dipartimento di Elettronica e Informazione of the Politecnico di Milano, prof. Paolo Paolini, working on the development of the online storytelling platform for e-learning “1001Storia”.

EDUCATION

- Ph.D. in Information Technology at Politecnico di Milano, Milano, Italy.
November 2013 - February 2017.
Title: *Semantic Modeling of the Global Structure of Buildings*
Advisor: *F. Amigoni*

Reviewers: *M. Hanheide (University of Lincoln), F. Pecora (University of Örebro)*

Thesis: <https://www.politesi.polimi.it/handle/10589/132104>

- M.Sc. in Computer Science Engineering at Politecnico di Milano, Milano, Italy.
September 2010 - December 2012 Grade: 110L/110.
Thesis title: *Semantic Labeling of Places Using Building Typology Knowledge in Mobile Robotics*,
Advisor *F. Amigoni*
- B.Sc. in Computer Science Engineering at Politecnico di Milano, Milano, Italy.
September 2007 - September 2010. Grade: 110L/110.
Thesis title: *Integration of Visual Landmarks in a ScanSLAM Algorithm*,
Advisor *M. Matteucci*
- High School diploma at Liceo Scientifico G.B.Grassi, Saronno, Italy. 2007. Grade: 89/100.

VISITING EXPERIENCES

- Visiting researcher at Department of Computer Science - Declarative Languages and Artificial Intelligence, Prof. Luc de Raedt, KU Leuven - June 2015.

EDUCATION - OTHERS

- Participation to the summer school on “Long-Term Autonomy for Mobile Robotics” (LAMoR), Lincoln Centre for Autonomous Systems (L-CAS), Lincoln University, UK (August/September 2015).
- Participation to the second Örebro Winter School on “Artificial Intelligence and Robotics” (LUCIA), Örebro Universitet, Sweden (December 2014).
- Exchange M.Sc student in Computer Science Engineering within the ERASMUS project at Chalmers Tekniska Hogskola, Göteborg, Sweden (August 2010 - January 2011).

SCHOLARSHIPS

- Scholarship from Ministero dell’Istruzione, dell’Università e della Ricerca for attending the XXIX PhD Cycle (November 2013 - November 2016).
- ERASMUS Scholarship as an exchange student at Chalmers Tekniska Hogskola, Göteborg, Sweden (August 2010 - January 2011).

Awards

- AW.1. Best paper award nomination for “Extracting Structure of Buildings using Layout Reconstruction” [IC.4], 15th International Conference on Intelligent Autonomous Systems (IAS-15), Baden-Baden (Germany), June 2018.
- AW.2. PhD Scholarship from Ministero dell’Istruzione, dell’Università e della Ricerca for attending the XXIX PhD Cycle at Dipartimento di Elettronica, Informazione e Bioingegneria, Politecnico di Milano, 2013.
- AW.3. Winner of the RoboCup Virtual Robot Competition Rescue Simulation League, RoboCup 2012, with “PoAReT”- Politecnico di Milano Autonomous Rescue Team [OH.2], Mexico City, June 2012.

Complete publication list

PUBLICATION LIST

Refereed international journals	JR
Refereed international conferences	IC
Workshops	WS
Others	OH

REFEREED INTERNATIONAL JOURNALS

- JR.1. Matteo Luperto, Francesco Amigoni, "Predicting the Global Structure of Indoor Environments: A Constructive Machine Learning Approach," *Autonomous Robots*, 2018.
doi: <https://doi.org/10.1007/s10514-018-9732-7>
- JR.2. Francesco Amigoni, Matteo Luperto, Viola Schiaffonati, "Towards Generalization of Experimental Results for Autonomous Robots," *Robotics and Autonomous Systems*, Vol. 90, no. 4, pp. 4-14, 2017.
doi: <https://doi.org/10.1016/j.robot.2016.08.016>

REFEREED INTERNATIONAL CONFERENCES

- IC.1. Matteo Luperto, Valerio Arcerito, Francesco Amigoni, "Predicting the Layout of Partially Observed Rooms from Grid Maps", *Proceedings of "IEEE International Conference on Robotics and Automation (ICRA-2019)"*, Montreal, Canada, May 2019 (Accepted).
- IC.2. Francesco Amigoni, Matteo Luperto, Danilo Fusi, N. Alberto Borghese, "Exploiting Inaccurate A Priori Knowledge in Robot Exploration", *Proceedings of "International Conference on Autonomous Agents and Multiagent Systems (AAMAS-2019)"*, Montreal, Canada, May 2019 (Accepted as extended abstract).
- IC.3. Francesco Amigoni, Matteo Luperto, Valerio Castelli, "Improving Repeatability of Experiments by Automatic Evaluation of SLAM Algorithms", *Proceedings of "IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS-2018)"*, Madrid, Spain, October 2018.
doi: <https://doi.org/10.1109/IROS.2018.8594189>
- IC.4. Matteo Luperto, Francesco Amigoni, "Extracting Structure of Buildings using Layout Reconstruction" *Proceedings of the 15th International Conference on Intelligent Autonomous Systems (IAS-15)*, Baden-Baden, Germany, June 2018.
doi: https://doi.org/10.1007/978-3-030-01370-7_51
- IC.5. Matteo Luperto, Marta Romeo, Nicola Basilico, Alberto Borghese, Angelo Cangelosi, Ray Jones, Simona Ferrante, Francesca Lunardini, "Digitalized Cognitive Assessment Mediated by a Virtual Caregiver," *Proceedings of the "International Joint Conference on Artificial Intelligence (IJCAI 2018)"*, demo track, Stockholm, Sweden, June 2018.
doi: <https://doi.org/10.24963/ijcai.2018/856>
- IC.6. Alessandro Vuono, Matteo Luperto, Jacopo Banfi, Nicola Basilico, Alberto Borghese, Micheal Sioutis, Jennifer Renoux, Amy Loufty, "Seeking Prevention of Cognitive Decline in Elders via Activity Suggestion by A Virtual Caregiver," *Proceedings of the "International Conference on Autonomous Agents and Multiagent Systems (AAMAS-2018)"*, demo track, Stockholm, Sweden, June 2018
- IC.7. Matteo Luperto, Alessandro Riva, Francesco Amigoni, "Semantic Classification by Reasoning on the Whole Structure of Buildings using Statistical Relational Learning Techniques," *Proceedings of the "IEEE International Conference on Robotics and Automation (ICRA 2017)"*, Singapore, Singapore, September 2017.
doi: <https://doi.org/10.1109/ICRA.2017.7989298>
- IC.8. Francesco Amigoni, Jacopo Banfi, Alessandro Longoni, Matteo Luperto, "Online Switch of Communication Modalities for Efficient Multirobot Exploration," *Proceedings of the "European Conference on Mobile Robotics (ECMR 2017)"*, Paris, France, September 2017.

doi: <https://doi.org/10.1109/ECMR.2017.8098699>

- IC.9. Matteo Luperto, Leone D’Emilio, Francesco Amigoni, “A Generative Spectral Model for Semantic Mapping of Buildings,” *Proceedings of “IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS-2015)”*, Hamburg, Germany, October 2015.
doi: <https://doi.org/10.1109/IROS.2015.7354009>
- IC.10. Matteo Luperto, Francesco Amigoni, “Exploiting Structural Properties of Buildings Towards General Semantic Mapping Systems,” *Proceedings of the “Thirteen International Conference on Intelligent Autonomous Systems (IAS-13)”*, Padova, Italy, July 2014.
doi: https://doi.org/10.1007/978-3-319-08338-4_28
- IC.11. Matteo Luperto, Francesco Amigoni, Alberto Quattrini Li, “A System for Building Semantic Maps of Indoor Environments Exploiting the Concept of Building Typology,” *Proceedings of the “RoboCup International Symposium (RoboCup 2013)”*, Eindhoven, Netherlands, July 2013.
doi: https://doi.org/10.1007/978-3-662-44468-9_44

WORKSHOPS

- WS.1. Matteo Luperto, Javier Monroy, Francisco-Angel Moreno, J.Raul Ruiz-Sarmiento, Nicola Basilico, Javier Gonzalez Jimenez, N.Alberto Borghese “A Multi-Actor Framework Centered around an Assistive Mobile Robot for Elderly People Living Alone,” *Workshop on Robots for Assisted Living, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2018)* , Madrid, Spain, October 2018.
- WS.2. Francesco Amigoni, Matteo Luperto, Valerio Castelli, Fabio Bonsignorio, “Predicting Robot Performance: Why and How,” *Federated AI for Robotics Workshop (joint IJCAI-ECAL/ICML/AAMAS Workshop)*, Stockholm, Sweden, July 2018.
- WS.3. Francesco Amigoni, Jacopo Banfi, Alessandro Longoni, Matteo Luperto, “Online Switch of Multirobot Communication Modalities for Efficient Exploration,” *Workshop on “Multi-robot Perception-Driven Control and Planning”, IEEE International Conference on Robotics and Automation (ICRA 2017)*, Singapore, June 2017.
- WS.4. Matteo Luperto, Francesco Amigoni, “A Constructive Machine Learning Approach for Robot Exploration and Search,” *Proceedings of the “IROS2015 (IEEE/RSJ International Conference on Intelligent Robots and Systems) Workshop on Machine Learning in Planning and Control of Robot Motion (MLPC17)”*, Hamburg, Germany, October 2015.
- WS.5. Francesco Amigoni, Matteo Luperto, Viola Schiaffonati, “Towards Generalization of Experimental Results for Autonomous Robots,” *IAS-13 (Thirteen International Conference on Intelligent Autonomous Systems) Workshop on “New Research Frontiers for Intelligent Autonomous Systems (NRF-IAS-2014)”*, Venezia, Italy, July 2014 .

OTHERS

- OH.1. Francesco Amigoni, Matteo Luperto, Alberto Quattrini Li, “Towards More Realistic Indoor Environments for the Virtual Robot Competition,” *RoboCup2014 Team Description Papers*, Joao Pessoa, Brasil, July 2014.
- OH.2. Francesco Amigoni, Alain Caltieri, Riccardo Cipolleschi, Riccardo Conconi, Michele Giusto, Matteo Luperto, Mladen Mazuran “PoAReT Team Description Paper,” *RoboCup2012 Team Description Papers*, Mexico City, Mexico, June 2012.

Teaching activity

2018-2019

Fondamenti Di Informatica - Prof. Cristiana Bolchini (*teaching assistant - assistente alla didattica - esercitazioni*) - Computer Engineering - Politecnico di Milano - Undergraduate level. (20h)
Years: 2018/2019.

2017-2018

Winter School on Industry 4.0: How the fourth industrial revolution will change the manufacturing environment - Prof. Marco Taish (*teaching assistant*) - Alta Scuola Politecnica (ASP), Politecnico di Torino and Politecnico di Milano - Higher education graduate level. (30h)
Year: 2017-2018.

2014-2018

Fondamenti Di Informatica - Prof. Cristiana Bolchini (*teaching assistant - responsabile di laboratorio*) - Computer Engineering - Politecnico di Milano - Undergraduate level. (18/20h)
Years: 2014/2015, 2015/2016, 2016/2017, 2017/2018.

2013-2017

Informatica B - Prof. Vittorio Zaccaria (*teaching assistant - responsabile di laboratorio*) - Mechanical and Energy Engineering - Politecnico di Milano - Undergraduate level. (18/20h)
Years: 2013/2014, 2014/2015, 2015/2016, 2016/2017.

2012-2013

Informatica B (*lab. tutor - tutor di laboratorio*) - Mechanical and Energy Engineering - Politecnico di Milano - Undergraduate level. (150h)
Year: 2012/2013.

STUDENTS' SUPERVISION

Graduate Students Supervision/Co-Advisor

- *Leone D'Emilio* 2014, "Un modello generative spettrale basato su grafi per il mapping semantico di edifici", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)
- *Michele Launi* 2015, "Reasoning on the whole structure of buildings using a Logical Relational Learning Framework", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)
- *Mattia Di Vitto, Modestino Cucciniello* 2015, "Modellazione e predizione di mappe semantiche di edifici tramite graph kernel e tecniche Monte Carlo Markov-Chain", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)
- *Matteo Calabrese* 2016, "Costruzione di Mappe Multilivello per Robot Mobili Autonomi", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)
- *Valerio Arcerito* 2017, "Modellazione e predizione della struttura di ambienti indoor per la robotica mobile a partire da una mappa parzialmente esplorata", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)
- *David Lorenzi* 2017, "The influence of starting position in single-robot exploration performances", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)
- *Matteo Pasina* 2017, "A system for automatically evaluating the quality of maps built by autonomous mobile robots", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)
- *Danilo Fusi* 2018, "Speeding up single-robot exploration performances using a-priori knowledge from blueprints", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)
- *Valerio Castelli* 2018, "Prediction of the map quality obtained from 2D SLAM", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)
- *Luca Fochetta* 2019 (expected - April), "Autonomous exploration of unknown environments exploiting map predictions", M.Sc. in Computer Science and Engineering, Politecnico di Milano (Italy)

Professional Activities

NATIONAL AND INTERNATIONAL RESEARCH PROJECTS

Matteo Luperto has contributed actively in the following research projects:

- *MoveCare - Multiple-Actors Virtual Empathic Caregiver for the Elder*,
PROGRAMME H2020-ICT-26B-2016
(Project Leader: prof. A. Borghese - AISLab - Università degli Studi di Milano)
- *RoboCup Rescue 2012: Autonomous Mobile Robots for Search and Rescue Application*,
FONDAZIONE BANCA DEL MONTE DI LOMBARDIA
(Project Leader: prof. F. Amigoni - AIRLab - Politecnico di Milano)

PROGRAM COMMITTEE MEMBERSHIP

Matteo Luperto was a member of the Program Committee of the following conferences:

- International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2019 (AAMAS19).

REFEREE SERVICES

Matteo Luperto is a reviewer for the following journals:

- Autonomous Robots, 2019.
- Interaction Studies, 2019.
- IEEE Transactions on Automation Science and Engineering (T-ASE), 2018.
- MDPI Applied Sciences, 2018, 2019.
- Robotics and Autonomous Systems, 2017.

Matteo Luperto is a reviewer for the following conferences:

- IEEE International Conference on Robotics and Automation, 2017 (ICRA2017), 2018 (ICRA2018), 2019 (ICRA2019).
- International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2019 (AAMAS19).
- IEEE/RSJ International Conference on Intelligent Robots and Systems, 2015 (IROS2015), 2016 (IROS2016), 2017 (IROS2017), 2018 (IROS2018).
- GNB, National Congress of Bioengineering, 2018 (GNB18).
- IEEE Symposium Series on Computational Intelligence, 2014 (SSCI2014).

MEMBERSHIPS

Matteo Luperto is member of the following associations:

- IEEE, the Institute of Electrical and Electronics Engineers.
- AI*IA, Associazione Italiana per l'Intelligenza Artificiale.

PARTICIPATION TO PROJECT MEETINGS

Matteo Luperto has attended the following conferences and meeting regarding the H2020 MoveCare project:

- MoveCare Program Steering Committee Meeting, University of Malaga, Malaga, Spain, January 2019.
- MoveCare Integration Meeting, University of Malaga, Malaga, Spain, January 2019.
- ICT-18, Wien, Austria, December 2018.
- MoveCare Integration Meeting, Università degli Studi di Milano, Milano, Italy, November 2018.
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Madrid, Spain, October 2018.
- MoveCare Technical Meeting for Robot Development, University of Malaga, Malaga, Spain, September 2018.
- International Joint Conference on Artificial Intelligence (IJCAI/ECAI), Stockholm, Sweden, July 2018.
- MoveCare Program Steering Committee Meeting, University of Örebro, Örebro, Sweden, June 2018.
- MoveCare Integration Meeting, Università degli Studi di Milano, Milano, Italy, January 2018.
- MoveCare Program Steering Committee Meeting, EURECAT Barcelona, Barcelona, Spain, November 2017.
- MoveCare Program Steering Committee Meeting, Signal Generix, Limassol, Cyprus, June 2017.
- European Robotic Forum (ERF), Edinburgh, Scotland, UK, March 2017.
- MoveCare Kick-off Meeting, Università degli Studi di Milano, Milano, Italy, January 2017.

CONTRIBUTION TO PILOT STUDIES

Matteo Luperto has contributed to the organization and management of the following pilot experiments with end-users for the H2020 MoveCare project, which aims to develop an assisted living framework integrating an autonomous mobile robot for the healthy aging of elders living at home:

- Testing of the Community Based Activity Center (CBAC) developed by the Applied Intelligent System Lab (AISLab) for the MoveCare project, second round of testing.
Description: during this pilot study we tested a multi-actor framework for cognitive, physical and social stimulation developed for elders living alone [IC.6]. We deployed the system in the house of 8 end-users of the platform, namely elders older than 65 years old and with no Mild Cognitive Impairment (MCI), collecting data about the system robustness and usability, while testing the improvements on the platform developed after a first pilot study, following the paradigm of continuous integration and human-centered design. Duration of the pilot study: 3 weeks, November 2018. Number of participants: 8.
- Testing of the use of an assistive robot for neuropsychological assessment of elders - joint collaboration with University of Manchester, University of Plymouth, and Politecnico di Milano - at the Assisted Living Lab of the Plymouth University, Plymouth, UK.
Description: during this pilot study we tested the use of an assistive robot as a supervisor and virtual caregiver for elders while doing a battery of cognitive tests. We collected data about the system robustness and usability. Preliminary results obtained during the development of the platform were presented at [IC.5], while the result of the pilot study is currently under review. Duration of the pilot study: 1 week, July 2018. Number of participants: 16.
- Testing of the digitalized version of cognitive tests for elders - joint collaboration with Fondazione IRCCS Cà Granda Ospedale Maggiore Policlinico and Dipartimento di Elettronica, Informazione e Bioingegneria, Politecnico di Milano - at the Policlinico Cà Granda Ospedale Maggiore, Reparto di Geriatria.
Description: during this pilot study we tested and validated against their paper-and-pencil counterparts the development of digitalized versions of cognitive tests for detecting MCI. The dataset acquired was consequently used for data analysis. The results of the pilot studies are currently under review in one journal and three conference papers. Duration of the pilot study: 1 year, October 2017 - October 2018. Number of participants: 83.
- Testing of the Community Based Activity Center (CBAC) developed by the Applied Intelligent System Lab (AISLab) for the MoveCare project, first round of testing.
Description: during this pilot study we tested a multi-actor framework for cognitive, physical and social stimulation developed for elders living alone [IC.6]. We deployed the system in the house of 8 end-users of the platform, namely elders older than 65 years old and with no MCI, collecting data about the system robustness and usability. Duration of the pilot study: 3 weeks, April 2018. Number of participants: 8.

Talks and Seminars

PRESENTATION AT INTERNATIONAL CONFERENCES

- “MoveCare - Multiple-Actors Virtual Empathic Caregiver for the Elder”, presented at ICT-2018, Wien, 2018.
- “Improving Repeatability of Experiments by Automatic Evaluation of SLAM Algorithms”, presented at the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2018), Madrid, 2018.
- “A Multi-Actor Framework Centered around an Assistive Mobile Robot for Elderly People Living Alone”, presented at the Workshop on Robots for Assisted Living, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2018), Madrid, 2018.
- “Digitalized Cognitive Assessment Mediated by a Virtual Caregive”, presented at the International Joint Conference on Artificial Intelligence (IJCAI 2018) - demo track, Stockholm, 2018.
- “Predicting Robot Performance: Why and How”, presented at the Federated AI for Robotics Workshop, joint IJCAI-ECAI/ICML/AAMAS Workshop (FAIR 2018), Stockholm, 2018
- “A Generative Spectral Model for Semantic Mapping of Buildings”, presented at the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2015), Hamburg, 2015.
- “A Constructive Machine Learning Approach for Robot Exploration and Search”, presented at the IROS2015 (IEEE/RSJ International Conference on Intelligent Robots and Systems) Workshop on Machine Learning in Planning and Control of Robot Motion (MLPC17), Hamburg, 2015.
- “Exploiting Structural Properties of Buildings Towards General Semantic Mapping Systems”, presented at the Thirteen International Conference on Intelligent Autonomous Systems (IAS-13), Padova, 2014.
- “Towards Generalization of Experimental Results for Autonomous Robots”, presented at IAS-13, Thirteen International Conference on Intelligent Autonomous Systems) Workshop on New Research Frontiers for Intelligent Autonomous Systems (NRF-IAS-2014), Venice, 2014.

SEMINARS

- “Towards long-term robot autonomy integrating AI and Robotics: the STRANDS example”, Dipartimento di Elettronica, Informazione e Bioingegneria, Politecnico di Milano (Italy), 2015.
- Lectures on “Audio techniques for Virtual Reality” for the course “Virtual Reality”, Prof. Alberto Borghese, Università degli Studi di Milano (Italy), years 2016/17 and 2017/2018, 6h.
- Presentation of the project “MoveCare - Multiple-Actors Virtual Empathic Caregiver for the Elder” at the course of “Startup and innovation”, Prof. Benassi, Università degli Studi di Milano (Italy), 2019.

Research interests

1 Reasoning about the structure of buildings for autonomous mobile robotics

Autonomous mobile robots can perform many different tasks to help humans during their activities or to replace them in hazardous environments and in simple routine operations. When we consider indoor tasks, robots have to interact with environments that are specifically designed for human activities and for interaction between humans, buildings.

Buildings are strongly structured environments that are organized in regular patterns. For instance, rooms typically have a geometrical structure that is characterized by features, such as walls perpendicular to the floor and to the ceiling, and by a layout that can be, in most cases, approximated by a box-like model.

In order to increase their ability to autonomously operate in indoor environments, robots must have a good understanding of buildings, in a way similar to the one that human beings exploit during their everyday activities. If we consider how people and robots interact with indoor environments, it can be said that people naturally understand and “read” buildings as human-made environments (and act in them accordingly) and that this is hardly the case for autonomous mobile robots.

Typically, the interaction between a robot and its environment is heavily based on data acquired with perception. Such data are used for constructing *metric* and *semantic maps* of the environment, where the former are used to represent the occupancy and the free space perceived by the robot, and the latter are abstract representations built on top of metric maps that aim to represent the meaning of parts of the perceived environment in order to provide robots a human-like understanding of their surroundings. Mapping methods usually provide reliable knowledge only on parts of the environment that have been already visited. This approach often implies that what has not been seen by the robot does not exist, adopting, in a sense, a closed world assumption on the environment. This form of interaction with the environment is radically different from that of humans, who can easily navigate and comprehend the structure of buildings even without having seen them before.

Our main research interest moves from the consideration that the global structure of buildings could be exploited to increase the autonomous abilities of robots when operating in indoor environments. Our proposed framework aims at identifying and at overcoming the limitations in standard mapping methods by starting from two insights on indoor environments. At first, we consider an entire floor of a building as a single object, by identifying relations between different (and potentially unconnected) parts of the building, such as walls, which can be used to infer the possible structure of unobserved parts of the building, as unexplored rooms behind closed doors [IC.3],[IC.1],[IC.4]. Moreover, we consider each building in relation to other buildings with the same function [JR.1]. The function of a building is represented by the main activity that each building is designed for (e.g., an office, a school) and is captured by the concept of *building type* [IC.11]. The function of a building imposes its structure, its floor plan, and the structure of its rooms. This allows us to exploit the fact that each building, having a precise function, shares some structural features with all other buildings with the same purpose [IC.7].

2 Assistive and collaborative autonomous mobile robotics

One of the long-term applications of autonomous mobile robots is to provide assistance during the execution of daily activities, both at home and in the workplace. The tasks that could already be performed by an autonomous mobile robots are numerous, such as providing guidance and instructions in large scale environment as museums or hospitals, providing stimulations and support to elders living at home, or function as collaborative robots (cobots) in an office environment. However, the long-term deployment of an autonomous robotic platform in a real-world scenario presents several issues dealing both with core abilities of the robot, as mapping and localization [IC.2], [IC.3], and with advanced functionalities such as human-robot interaction [IC.5], task planning, and autonomous decision making. Moreover, the interaction of a robotic platform with IoT-based smart environments could increase the set of the possible application of robotic platforms [WS.1]. Up to now, a proper methodology for testing and assessing the correct long-term and large-scale functioning of such robots is still largely missing [JR.2]. Our research aims to address several of the current limitations of assistive and collaborative autonomous mobile robots, by analysing and evaluating the robot performances in new and different environments [IC.3] [JR.2], and by developing functionalities for assistive robots [WS.1].